CLASS : XITh
Solutions

## TOpic :- SYSTEM OF PARTICLES AND ROTATIONAL MOTION

1
(d)

Let $a$ be acceleration of fall of the thread, then net force acting downwards, balances the force due to tension ( $T$ ) in the thread.


$$
\begin{align*}
& m g-T=m a \\
\Rightarrow \quad & m g-m a=T \tag{i}
\end{align*}
$$

Also torque (also known as moment or couple acts on the system).
$\tau=$ force $\times$ perpendicular distance axis of rotation

$$
\tau=T \times R
$$

From Eq. (i),

$$
\begin{equation*}
\tau=m(g-a) \times R \tag{ii}
\end{equation*}
$$

Let $I$ is moment of inertia of reel and $\alpha$ the angular acceleration, then torque is

$$
\begin{equation*}
\tau=I \alpha \tag{iii}
\end{equation*}
$$

where, $I=\frac{1}{2} M R^{2}, \alpha=\frac{a}{R}$
$\therefore \quad \tau=\frac{1}{2} M R^{2} \times \frac{a}{R}=\frac{M R a}{2}$
Equating Eqs. (ii) and (iv), we get

$$
\begin{aligned}
& \tau=m(\mathrm{~g}-a) R=\frac{m R a}{2} \\
\Rightarrow & \mathrm{~g}-a=\frac{a}{2} \\
\Rightarrow & \quad a=\frac{2}{3} \mathrm{~g}
\end{aligned}
$$

(c)

Force of attraction between two stars
$F=\frac{G m_{1} m_{2}}{\left(r_{1}+r_{2}\right)^{2}}$

Acceleration $=\frac{F}{m_{1}}=\frac{G m_{2}}{\left(r_{1}+r_{2}\right)^{2}}$
(c)

Here, $m_{1}=m_{2}=0.1 \mathrm{~kg}$

$$
\begin{gathered}
r_{1}=r_{2}=10 \mathrm{~cm}=0.1 \mathrm{~m} \\
I=I_{1}+I_{2}=m_{1} r_{1}^{2}+\frac{1}{2} m_{2} r_{2}^{2}=\frac{3}{2} m_{1} r_{1}^{2} \\
=\frac{3}{2} \times 0.1(0.1)^{2}=1.5 \times 10^{-3} \mathrm{~kg} \mathrm{~m}^{2}
\end{gathered}
$$

(a)

For solid sphere, $\frac{K^{2}}{R^{2}}=\frac{2}{5}$
For disc and solid cylinder, $\frac{K^{2}}{R^{2}}=\frac{1}{2}$
As $\frac{K^{2}}{R^{2}}$ for solid sphere is smallest, it takes minimum time to reach the bottom of the incline
(a)

$$
I=\frac{1}{2} M R^{2}=\frac{1}{2} \times\left(\pi R^{2} t \times \rho\right) \times R^{2}
$$

$\Rightarrow I \propto R^{4} \quad$ (As $t$ and $\rho$ are same)

$$
\therefore \frac{I_{1}}{I_{2}}=\left(\frac{R_{1}}{R_{2}}\right)^{4}=\left(\frac{0.2}{0.6}\right)^{4}=\frac{1}{81}
$$

(c)
$m_{1} r_{1}=m_{2} r_{2}$
$\frac{r_{1}}{r_{2}}=\frac{m_{2}}{m_{1}} \quad \therefore r \propto \frac{1}{m}$
(d)

According to law of conservation of angular momentum, if there is no torque on the system, then the angular momentum remains constant.
(b)

Let the mass of an element of length $d x$ of rod located at a distance $x$ away from left end is $\frac{M}{L} d x$. The $x$-coordinate of the centre of mass is given by

(c)

As $\overrightarrow{\mathrm{F}}_{\text {ext }}=0$, hence momentum remains conserved and final momentum = initial momentum $=m v$
(a)

The moment of inertia of this annular disc about the axis perpendicular to its plane will be
$\frac{1}{2} M\left(R^{2}+r^{2}\right)$.
(b)

Since, rod is bent at the middle, so each part of it will have same length $\left(\frac{L}{2}\right)$ and mass $\left(\frac{M}{2}\right)$ as shown.


Moment of inertia of each part through its one end

$$
=\frac{1}{3}\left(\frac{M}{2}\right)\left(\frac{L}{2}\right)^{2}
$$

Hence, net moment of inertia through its middle point $O$ is

$$
\begin{aligned}
I & =\frac{1}{3}\left(\frac{M}{2}\right)\left(\frac{L}{2}\right)^{2}+\frac{1}{3}\left(\frac{M}{2}\right)\left(\frac{L}{2}\right)^{2} \\
& =\frac{1}{3}\left[\frac{M L^{2}}{8}+\frac{M L^{2}}{8}\right]=\frac{M L^{2}}{12}
\end{aligned}
$$

(c)
$K=\frac{L^{2}}{2 I}=\frac{K_{1}}{K_{2}}=\frac{L_{1}^{2}}{L_{2}^{2}} \Rightarrow \frac{K_{1}}{K_{2}}=\left(\frac{100}{110}\right)^{2}=\frac{100}{121}$
$\Rightarrow \frac{100}{K^{2}}=\frac{100}{121} \Rightarrow K_{2}=121=100+21$
Increase in kinetic energy $=21 \%$

$$
K_{\mathrm{rot}}=\frac{1}{2} I \omega^{2}=\frac{1}{2}\left(\frac{1}{2} M R^{2}\right) \omega^{2}=\frac{1}{4} M R^{2} \omega^{2}
$$

The translational kinetic energy is

$$
K_{\text {trans }}=\frac{1}{2} M v_{\mathrm{CM}}^{2}
$$

where $v_{\mathrm{CM}}$ is the linear velocity of its centre of mass.
Now, $v_{\mathrm{CM}}=R \omega$
Therefore, $\quad K_{\text {trans }}=\frac{1}{2} M R^{2} \omega^{2}$
Thus, $K_{\text {total }}=\frac{1}{4} M R^{2} \omega^{2}+\frac{1}{2} M R^{2} \omega^{2}=\frac{3}{4} M R^{2} \omega^{2}$
$\therefore \quad \frac{K_{\text {rot }}}{K_{\text {total }}}=\frac{\frac{1}{4} M R^{2} \omega^{2}}{\frac{3}{4} M R^{2} \omega^{2}}=\frac{1}{3}$
(c)

$$
L=I \omega
$$

(c)

Since force is not acting on centre of mass, it will produced torque hence linear and angular acceleration both will change
(a)

$$
\begin{aligned}
& m g h=\frac{1}{2} I \omega^{2}+\frac{1}{2} m v^{2} \\
& =\frac{1}{2}\left(\frac{2}{5} m r^{2}\right) \omega^{2}+\frac{1}{2} m v^{2}=\frac{7}{10} m v^{2} \\
& \therefore v=\sqrt{\frac{10}{7} g h}
\end{aligned}
$$

(c)

For the rolling a solid cylinder acceleration $a=\frac{\mathrm{g}}{3} \sin \theta$

$\therefore$ The condition for the cylinder to remain in equilibrium
$M a \leq \mu s R$
$\Rightarrow \quad \frac{1}{2} M g \sin \theta \leq M g \cos \theta \cdot \mu_{\mathrm{s}}$
or $\quad \mu_{s} \geq \frac{1}{3} \tan \theta$
or $\quad \tan \theta \leq 3 \mu_{s}$
(d)

Since, no external force is present on the system so, conservation principle of momentum is applicable
$\therefore \overrightarrow{\mathrm{p}}_{i}=\overrightarrow{\mathrm{p}}_{f}=\overrightarrow{\mathrm{p}}_{1}+\overrightarrow{\mathrm{p}}_{2}$
$\therefore \overrightarrow{\mathrm{p}}_{1}=-\overrightarrow{\mathrm{p}}_{2} \quad\left(\because \mathrm{p}_{i}=0\right)$
$\therefore\left|\overrightarrow{\mathrm{p}}_{1}\right|=\left|-\overrightarrow{\mathrm{p}}_{2}\right|$
$\therefore \overrightarrow{\mathrm{p}}_{1}=\overrightarrow{\mathrm{p}}_{2}$
From this point of view, it is clear that momenta of both particles are equal in magnitude but opposite in direction
Also, friction is absent. So total mechanical energy of system remains conserved

| ANSWER-KEY |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Q. | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |  |  |
| A. | D | C | C | A | A | C | D | B | C | A |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |
| Q. | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |  |  |
| A. | B | C | C | A | A | C | C | A | C | D |  |  |
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