

DPP

DAILY PRACTICE PROBLEMS

CLASS : XIth
DATE :

Solutions

SUBJECT : PHYSICS
DPP No. : 8

Topic :- LAWS OF MOTION

1 (b)

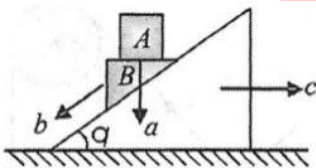
For A:

$$5g - T = 5(2C)$$

$$\text{For C: } 2T - 8g = 8C \Rightarrow C = \frac{8}{14} = \frac{5}{7} \text{ ms}^{-2}$$

2 (b)

1. Acceleration of block A downwards w.r.t. ground



2. Acceleration of block B w.r.t. inclined plane

3. Acceleration of block C w.r.t. ground right side. $\vec{b} + \vec{c}$ acceleration of B w.r.t. ground

Applying Newton's law on system along horizontal direction, we have

$$mc + m(c - b \cos \theta) = 0 \quad \text{(i)}$$

Applying Newton's law on (A + B) along the inclined plane,

$$2mg \sin \theta = m(b - c \cos \theta) + ma \sin \theta$$

$$2g \sin \theta = b - c \cos \theta + a \sin \theta \quad \text{(ii)}$$

From wedge constraint between A and B,

$$a = b \sin \theta \quad \text{(iii)}$$

$$\text{From Eq. (i), (ii) and (iii), } b = \frac{4g \sin \theta}{1 + 3 \sin^2 \theta}$$

3 (a)

For chain to move with constant speed, P needs to be equal to frictional force on the chain.

As the length of chain on the rough surface increases. Hence, the friction force $f_k = \pi_k N$ increases

4

(d)

Let at any time, their velocities are v_1 and v_2 , respectively, then $v_1 = v_2 \cos \theta$

Differentiating: $a_1 = a_2 \cos \theta - v_2 \sin \theta \frac{d\theta}{dt}$

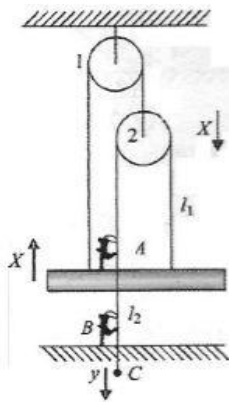
Hence, none of them is correct

[Note: Option (a) is correct initially, because initially $v_2 = 0$]

5

(c)

Let the plank move up by x , then pulley 2 will move down by x . Let the end of string C moves down by a distance y



Let the initial length of string passing over pulley 2 $l_1 + l_2$ (i)

After displacement x and y mentioned above, the lengths becomes

$(l_1 - 2x) + (l_2 + y - x)$ (ii)

Equating (i) and (ii), we get $y = 3x$

Length of string that slips through A is $y + x = 4x$

Length of string that slip[s through A is $y + x = 4x$ and the through B is $y = 3x$

Required ratio $\frac{4x}{3x} = \frac{4}{3}$

6

(b)

Horizontal acceleration of the system is

$$a = \frac{F}{2m + m + 2m} = \frac{F}{5m}$$



Let N be the normal reaction between B and C. Free-body diagram of C gives

$$N = 2ma = \frac{2}{5}F$$

Now B will not slide downwards if $\mu N \geq mg$

Or $\mu \left(\frac{2}{5}F\right) \geq mg$ or $F \geq \frac{5}{2\mu}mg$

Or $F_{\min} = \frac{5}{2\mu}mg$

7

(b)

$$t_A = \sqrt{\frac{2s}{a_A}} \Rightarrow t_D = \sqrt{\frac{2s}{a_D}}, t_A = \frac{1}{2}t_D$$

$$\sqrt{\frac{2s}{g \sin \theta + \mu g \cos \theta}} = \frac{1}{2} \sqrt{\frac{2s}{g \sin \theta - \mu g \cos \theta}}$$

$$4g \sin \theta - 4\mu g \cos \theta = g \sin \theta + \mu g \cos \theta$$

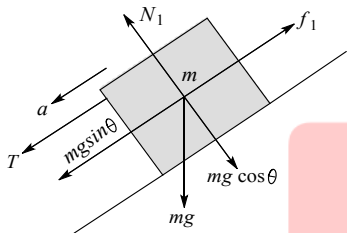
$$3g \sin \theta = 5\mu g \cos \theta \text{ or } \mu = \frac{3}{5} \tan \theta = \frac{3}{5}$$

($\therefore \theta = 45^\circ$)

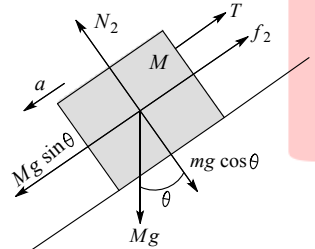
8

(c)

$$N_1 = mg \cos \theta \text{ and } f_1 = \mu mg \cos \theta$$



$$N_2 = Mg \cos \theta \text{ and } f_2 = \mu Mg \cos \theta$$



Equation of motion are

$$T - f_1 = mgsin \theta = ma \quad (i)$$

$$Mgsin \theta - T - f_2 = Ma \quad (ii)$$

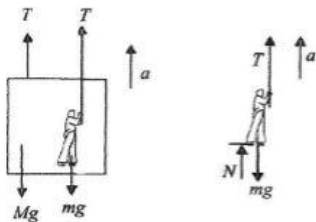
Solving Eqs. (i) and (ii), we get $T = 0$

9

(a)

$$2T - (M + m)g = (M + m)a \quad (i)$$

$$T - mg + N = ma \quad (ii)$$



From (i) and (ii), we get

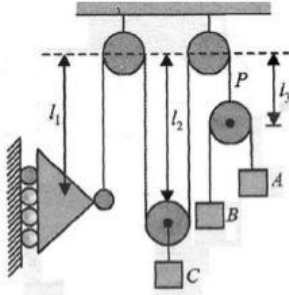
$$N = \left(\frac{m - M}{2}\right)(g + a) > 0$$

As $m > M$, if T increase, a increase and if a increase N increases

10

(d)

Using constraint theory



$$l_1 + 2l_2 + l_3 = \text{constant}$$

$$\Rightarrow v_1 + 2v_2 + v_3 = 0$$

Take downward as positive and upward as -ve

$$\text{So } +12 + 2(-4) + v_3 = 0$$

$$v_3 = \text{velocity of pulley } P = -4 \text{ ms}^{-1}$$

$$= 4 \text{ ms}^{-1} \text{ In upward direction}$$

$$\vec{v}_{AP} = -\vec{v}_{BP} \Rightarrow v_{AP} = -(v_B - v_P)$$

$$v_B = v_P - v_{AP} = -4 - (-3) = -7 \text{ ms}^{-1}$$

i.e., block B is moving up with speed 7 ms^{-1}

11

(d)

$$\vec{v}_{B,1} = 4 \text{ ms}^{-1} \uparrow, \vec{V}_{B,1} = \vec{V}_B, g - \vec{V}_P, g$$

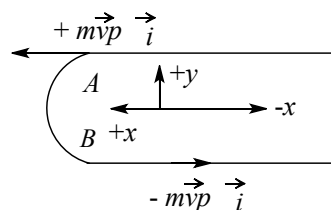
$$\Rightarrow 4 \text{ ms}^{-1} = \vec{V}_{B,g} - 2 \text{ ms}^{-1}; \vec{V}_{B,g} = 6 \text{ ms}^{-1} \uparrow$$

12

(b)

Choosing the positive $x - y$ axis as shown in the figure, the momentum of the bead at A is \vec{p}_i

$= + m\vec{v}$. The momentum of the bead at B is $\vec{p}_f = - m\vec{v}$



Therefore, the magnitude of the change in momentum

$$\text{Between A and B is } \Delta\vec{p} = \vec{p}_f - \vec{p}_i = -2m\vec{v}$$

i.e., $\Delta p = 2mv$ along the positive x -axis

the time taken by the bead to reach from A to B is

$$\Delta t = \frac{\pi d/2}{v} = \frac{\pi d}{2v}$$

Therefore, the average force exerted by the bead on the wire is

$$F_{av} = \frac{\Delta p}{\Delta t} = \left(2mv / \frac{\pi d}{2v}\right) = \frac{4mv^2}{\pi d}$$

13 **(d)**

The acceleration of block-rope system is $a = \frac{F}{(M+m)}$

Where M is the mass of block and m is the mass of rope

So the tension in the middle of the rope will be

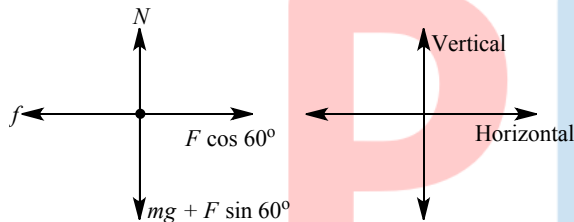
$$T = \{M + (m/2)\}a = \frac{M + (m/2)F}{M + m}$$

Given that $m = M/2$

$$\therefore T = \left[\frac{M + (M/4)}{M + (M/2)}\right]F = \frac{5F}{6}$$

14 **(a)**

Free body diagram (FBD) of the block (shown by a dot) is shown in figure.



For vertical equilibrium of the block,

$$N = mg + F \sin 60^\circ = \sqrt{3}g + \sqrt{3}\frac{F}{2} \dots(i)$$

For no motion, force of friction

$$f \geq F \cos 60^\circ$$

$$\text{or } \mu N \geq F \cos 60^\circ$$

$$\text{or } \frac{1}{2\sqrt{3}} \left(\sqrt{3}g + \frac{\sqrt{3}F}{2} \right) \geq \frac{F}{2}$$

$$\text{or } g \geq \frac{F}{2} \text{ or } F \leq 2g \text{ or } 20 \text{ N}$$

Therefore, maximum value of F is 20 N.

15 **(a)**

Applying Newton's law on system along horizontal direction, we have

$$mc + m(c - b \cos \theta) = 0 \quad (i)$$

$$c = \frac{b \cos \theta}{2}$$

16 **(a)**

During downward motion:

$$F = mg \sin \theta - \mu mg \cos \theta$$

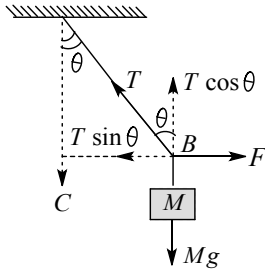
During upward motion:

$$2F = mg \sin \theta + \mu mg \cos \theta$$

Solving above two equations, we get $m = (\tan \theta)/3$

17 (b)

In figure, the point B is in equilibrium under the action of T, F and Mg



Here $T \sin \theta = F$ or $T = F / \sin \theta$

18 (c)

$$a_1 = \frac{F - f}{m_1} = \frac{F - \mu m_1 g}{m_1} = 10 \text{ ms}^{-2}$$

$$a_2 = \frac{F - \mu m_2 g}{m_2} = 1 \text{ ms}^{-2}$$

$$\therefore s = \frac{1}{2} a_{\text{real}} t^2 = \frac{1}{2} [10 + 1] t^2 \Rightarrow t = 2 \text{ s}$$

19 (c)

Due to acceleration in forward direction, vessel is in an accelerated frame therefore a Pseudo force will be exerted in backward direction. Therefore water will be displaced in backward direction

20 (a)

$x = 0$, till $mg \sin \theta < \mu mg \cos \theta$ and gradually x will increase. At angle $\theta > \tan^{-1}(\mu)$

$$kx + \mu mg \cos \theta = mg \sin \theta$$

$$\text{or } x = \frac{mg \sin \theta - \mu mg \cos \theta}{k}$$

Here k is the force constant of spring

ANSWER-KEY										
Q.	1	2	3	4	5	6	7	8	9	10
A.	B	B	A	D	C	B	B	C	A	D
Q.	11	12	13	14	15	16	17	18	19	20
A.	D	B	D	A	A	A	B	C	C	A

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